Programmatic Strategy Synthesis Resolving Nondeterminism in Probabilistic Programs

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Markov decision processes (MDPs) are a standard model for sequential decision making and planning in probabilistic environments. A fundamental MDP problem is to find a decision rule -a *strategy* - that performs well according to a given criterion. In this talk, we are concerned with synthesizing strategies for infinite parameterized families of MDPs. For example, in a gambling game we may not know our initial budget upfront, and would like to have a *parametric strategy*, i.e, one for each possible initial budget. We encode such families of MDPs as well as the corresponding strategies as imperative programs extended with coin flips and nondeterministic branchings. The latter are used to model the agent's decisions as can be seen in the example further below.

Our approach draws on principles from deductive program verification, most prominently preand postconditions as well as loop invariants. The technique yields strategies with mathematically provable performance guarantees and can be automated if all loops occurring in the program are annotated with suitable (user-provided) invariants.

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while
$$c < N \land a = 0 \rightarrow \{$$
 w
if true
 $\rightarrow \{c := c + 1\} [p] \{a := 1\}$
if true
 $\rightarrow \{c := c + 2\} [q] \{a := 1\}$
}

Program modeling a gamble which is won as soon as $c \ge N$ tokens are collected and lost once *a* is set to 1. The two "true" branches model a choice of the gambler. Statements of the form $\{...\}$ [*p*] $\{...\}$ represent a probabilistic choice. The initial values of *c*, *N*, *p*, and *q* are arbitrary parameters.

while
$$c < N \land a = 0 \rightarrow \{$$

if $(q \le p^2) \lor (p^2 < q < p \land N - c \text{ is odd})$
 $\rightarrow \{c := c + 1\} [p] \{a := 1\}$
if $(p \le q) \lor (q = p^2) \lor (p^2 < q < p \land N - c \ge 2)$
 $\rightarrow \{c := c + 2\} [q] \{a := 1\}$

Parametric strategy represented as a refined version of the program on the left. The gambler is guaranteed to win with highest possible probability if decisions consistent with the red predicates are made. This works for arbitrary initial values of c, N, p, and q.

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